# STUDY OF ATMOSPHERIC BOUNDARY LAYER OVER HONG KONG USING MOBILE MICRO-PULSE LIDAR

CHAN CHIU SHING

MASTER OF PHILOSOPHY

CITY UNIVERSITY OF HONG KONG

November 2005

## CITY UNIVERSITY OF HONG KONG 香港城市大學

## Study of Atmospheric Boundary Layer over Hong Kong Using Mobile Micro-Pulse Lidar 使用流動微脈衝激光雷達研究香港 大氣邊界層

Submitted to Department of Physics and Materials Science 物理及材料科學學系 in Partial Fulfillment of the Requirements for the Degree of Master of Philosophy 哲學碩士學位

by

Chan Chiu Shing 陳潮成

November 2005 二零零五年十一月

#### Abstract

Study of the boundary layer height, also known as the mixed layer height or mixing height, is of most importance to air pollution research and numerical modelling. In order to measure the mixing heights at various locations in Hong Kong, an eye-safe mobile micro-pulse lidar has been developed and deployed in field campaigns. In this thesis, the principle of lidar operation and our eye-safe mobile micro-pulse lidar design are introduced. These mobile lidar measurements are the first of their kind in Hong Kong. The advantages and limitations of using mobile lidar for mixing height determination are studied and discussed. To investigate the seasonal variation as well as the difference in mixing height at different locations, one-year periodic measurements were made at four selected sites located at the extreme edges of Hong Kong for a collaboration project with the Environmental Protection Department (EPD) during year 2003. The results show that there is a general seasonal trend of the daily maximum mixing height (MMH) among the sites. The MMH was found to be related to the temperature, wind speed and relative humidity of the atmosphere. For example, the MMH in autumn is generally the highest because of warm and dry conditions. The seasonal trend at one particular site is inconsistent with the general trend, and it will be explained in detail. Diurnal variations of the mixing height were observed and analysed with reference to meteorological parameters provided by the Hong Kong Observatory (HKO). Strong correlation between the diurnal variation and the temperature change was found. To verify our lidar data, comparisons were made with radiosonde data provided by the HKO. In addition, a road trip campaign was conducted at eight selected sites in the New Territories region of Hong Kong along a major highway during 2004 and 2005 and the results are presented.

### Contents

ABS	STRAC	CT	I	
LIS	T OF 1	TABLES	V	
LIS	T OF I	FIGURES	VI	
SYN	1BOL	S AND ACRONYMS	IX	
1.	INT	RODUCTION	1	
	1.1	METEOROLOGICAL REMOTE SENSING INSTRUMENTS		
	1.2	PRINCIPLE MECHANISM OF LIDAR		
	1.3	Types and History of Lidars		
	1.4	IMPORTANCE OF AEROSOL MEASUREMENT	5	
	1.5	Advantages of Lidar	6	
	1.6	OBJECTIVES AND LAYOUT OF THE THESIS	6	
2.	BAC	CKGROUND THEORY AND CALCULATION		
	2.1	Atmospheric Structure		
	2.2	ATMOSPHERIC BOUNDARY LAYER (MIXING LAYER)		
	2.3	IMPORTANCE OF BOUNDARY LAYER MEASUREMENT		
	2.4	MAJOR TYPES OF SCATTERING IN THE ATMOSPHERE		
		2.4.1 Introduction		
		2.4.2 Elastic Scatterings		
		2.4.3 Inelastic Scattering		
	2.5	AEROSOL MEASUREMENT BY LIDAR		
		2.5.1 Introduction		
		2.5.2 Lidar Equations		
		2.5.3 Lidar Inversion Methods		
		2.5.4 Growth of the Mixing layer		
3.	MO	MOBILE LIDAR SYSTEM AT CITY UNIVERSITY		
	3.1	MOBILE LIDAR SYSTEM SPECIFICATIONS		
	3.2	PHOTON COUNTING CORRECTIONS		
	3.3	NEAR RANGE CORRECTIONS		
4.	ERROR ANALYSIS			
	4.1	Sources of Error		
	4.2	Error Reductions		
	4.3	RANGE ERROR IN LIDAR MEASUREMENTS		

5.	MIX	ING HEIGHT DETERMINATIONS	39
	5.1	DETERMINATION OF THE MIXING HEIGHT FROM RADIOSONDE PROFILES	39
	5.2	DETERMINATION OF THE MIXING HEIGHT FROM LIDAR EXTINCTION PROFILES	41
	5.3	DIFFICULTIES IN ESTIMATING THE MIXING HEIGHT FROM THE LIDAR PROFILES	43
		5.3.1 Estimating the Low Level Cumulus Cloud Base Height	44
		5.3.2 Cloud Removal by the Method of Weighted Averaging	46
6.	RESULTS AND DISCUSSIONS		50
	6.1	COMPARISON OF THE MIXING HEIGHTS (CITYU VS. RADIOSONDE)	50
	6.2	COMPARISON OF THE MIXING HEIGHTS (RADIOSONDE VS. SITES DATA)	53
	6.3	THREE-HOUR CONTINUOUS MEASUREMENT AT BLACK POINT	56
	6.4	MONTHLY MAXIMUM MIXING HEIGHT MEASURED AT CITYU	60
	6.5	10-MINUTE QUICK SCANNING AT DIFFERENT SITES IN THE NEW TERRITORIES	61
	6.6	DIURNAL VARIATION OF THE MIXING HEIGHT	66
	6.7	MAXIMUM MIXING HEIGHT MEASURED AT THE FOUR SITES	78
LIST	ſ OF F	PUBLICATIONS	91
REF	EREN	ICES	93
APP	ENDI	X	98

#### **List of Tables**

- **Table 2.1**Comparisons between the Rayleigh and Mie scattering.
- **Table 6.1**Mixing height (km) at the 8 selected sites in the NT area.
- **Table 6.2**Meteorological information relevant to the NT road trip.
- **Table 6.3**Summary of the mixing heights measured on 11 November 2004.
- **Table 6.4**Parameters of the second order polynomials curve fitting for the diurnal<br/>variation of the mixing height and the related meteorological values<br/>provided by HKO.
- **Table 6.5**Summary of daily MMH measured at BP.
- **Table 6.6**Summary of daily MMH measured at TBT.
- **Table 6.7**Summary of daily MMH measured at HH.
- **Table 6.8**Summary of daily MMH measured at HT.
- **Table 6.9**Statistics of the mixing height measured in each month.

#### **List of Figures**

- Figure 1.1 Lidar operation principle.
- Figure 2.1 Structure of atmosphere and its temperature profiles.
- Figure 2.2 Different parts of boundary layer under high pressure region.
- **Figure 2.3** Graphs of typical early morning sounding and sensible surface heat flux for convective mixing height estimation.
- Figure 3.1 Schematic of the CityU mobile lidar setup.
- **Figure 3.2** Photo of the previous lidar setup inside the van.
- Figure 3.3 Photo of the latest lidar setup inside the van.
- Figure 3.4 Appearance of the mobile lidar van.
- **Figure 3.5** Screen capture of data logging software showing analogue and photon-counting channels.
- Figure 3.6 Photon-counting signal correction against analogue signal.
- **Figure 3.7** Logarithmic range corrected signal against range for open iris size (red solid line represents the ideal line and blue data are horizontal lidar measurements toward ocean on 5 Nov 2004 at Luk Keung).
- Figure 3.8 Near range correction to logarithmic range corrected signal  $[S=ln(r^2p)]$  for different iris sizes (measured on 5 Nov 2004 at Luk Keung).
- **Figure 4.1** The interfacing program panel showing a constant noise level offset at far range from 4 km to 7.6 km.
- **Figure 5.1** Typical potential temperature profile in unstable atmospheric condition.
- **Figure 5.2** Typical potential temperature profile in near neutral or slightly stable atmospheric condition.
- **Figure 5.3** Mixing height in ideal lidar extinction profile [the ideal extinction profile equation is adopted from *Steyn et al.*(1999).]
- **Figure 5.4** Mixing height in lidar extinction profile with an extinction peak caused by low level cloud (the mixing height is estimated at the height where the first local maximum occurs).
- **Figure 5.5** Typical extinction coefficient profile with a cloud peak (in this profile, the weighted averaging is not applied).

**Figure 6.1** Map of the measurement sites for the EPD project (locations of our campus and HKO are also indicated).

5.5, after averaging by inverse variance weighting.

- **Figure 6.2** Comparison of mixing heights detected with radiosondes at King's Park meteorological station and lidar at CityU in the year of 2003.
- Figure 6.3 Radiosonde data profiles of the outlier case.

Figure 5.6

- Figure 6.4 Lidar extinction coefficient profile of the outlier case.
- **Figure 6.5** Comparison between the mixing heights obtained from lidar data measured at BP and the mixing heights obtained from the radionsonde profiles measured by HKO.
- **Figure 6.6** Comparison between the mixing heights obtained from lidar data measured at TBT and the mixing heights obtained from the radionsonde profiles measured by HKO.
- **Figure 6.7** Comparison between the mixing heights obtained from lidar data measured at HH and the mixing heights obtained from the radionsonde profiles measured by HKO.
- **Figure 6.8** Comparison between the mixing heights obtained from lidar data measured at HT and the mixing heights obtained from the radionsonde profiles measured by HKO.
- **Figure 6.9** Plot of the logarithmic range adjusted power variable *S* against range for the analogue and photon counting channels at 18:00 on 25 Oct 2003 (The dashed line represents the photon counting saturation limit).
- **Figure 6.10** Extinction coefficient profile (solid line) and it estimated error (dotted line).
- Figure 6.11 Three-hour continuous extinction coefficient measurements starting from 18:00 on 25 October 2003.
- Figure 6.12 Three-hour continuous extinction coefficient measurements starting from 06:00 on 26 October 2003.
- Figure 6.13 Average MMH in the months of year 2003.
- Figure 6.14 Map of the 8 measurement sites around the NT region.
- **Figure 6.15** Mixing heights measured at the 8 selected sites in the NT area (plotted in reverse order of measurement time).

- Figure 6.16 Diurnal variation of the mixing height measured at CityU on 11 November 2004.
- Figure 6.17 Correlation between the mixing heights and the temperatures measured at CityU on 11 November 2004.
- **Figure 6.18** Diurnal change of the mixing height measured at BP on 7 March 2003 and variations of other meteorological parameters at the same time period.
- **Figure 6.19** Diurnal change of the mixing height measured at TBT on 19 June 2003 and variations of other meteorological parameters at the same time period.
- **Figure 6.20** Diurnal change of the mixing height measured at HH on 5 July 2003 and variations of other meteorological parameters at the same time period.
- **Figure 6.21** Diurnal change of the mixing height measured at HT on 30 Oct 2003 and variations of other meteorological parameters at the same time period.
- **Figure 6.22** Comparison between the FWHM of the diurnal variation in mixing height and the mean percentage cloud coverage of the day provided by HKO.
- **Figure 6.23** Comparison between the MMH and the daily global solar radiation provided by HKO.
- **Figure 6.24** MMHs measured at HH during the year of 2003 with the daily mean of some meteorological parameters provided by HKO.
- **Figure 6.25** Graph of MMHs estimated by the regression equation against the real values measured at HH during the year of 2003.
- **Figure 6.26** Seasonal variation of the MMH measured at the four sites. (all the data shown were measured in 2003 except the November data in BP which was measured in 2002). Bars represent variability in the data (one standard deviation) rather than experimental errors.

## Symbols and Acronyms

α	extinction coefficient
$lpha_A$	fraction of active cloud coverage
β	backscatter coefficient
λ	wavelength
η	net volumetric flow rate
ρ	density of the fluid
θ	potential temperature
τ	optical thickness
μ	magnetic permeability
σ	standard deviation
$\sigma_r$	Rayleigh scattering cross-section
$\sigma_m$	Mie scattering cross-section
$\overline{w' \theta_s'}$	the sensible heat flux on the earth's surface
A	absorption coefficient
а	radius of the scattering particle
$A_e$	effective system receiver area
С	the calibration constant of the lidar setup
С	the velocity of light
Ε	laser pulse energy
е	vapour pressure
$e_s$	saturated vapour pressure
$h_n$	spherical Hankel functions
Ι	intensity of radiation

$I_o$	initial intensity of the radiation before entering the media
$j_n$	spherical Bessel functions
k	the wavenumber
$L_{v}$	specific latent heat of vaporization at 0°C
т	ratio of the refractive index of the particle to that of the surrounding medium
Р	received power of the lidar
р	pressure
$p_o$	ground level pressure
$R_{v}$	specific gas constant for water vapour
r	range
$\Delta r$	range error of the lidar setup
δr	range resolution of the lidar setup
S	logarithmic range adjusted power variable
$S_{I}$	lidar ratio (equal to BER)
Т	temperature
$T_o$	ground level temperature
$T_d$	dew point temperature
t	travelling time of laser pulse
ť	difference in the travelling time of laser pulse
δt	time resolution of the lidar setup
$\Delta t$	time error of the lidar setup
u	flow velocity
Wi	weighting factor of averaging
W <sub>c</sub>	the average vertical velocity within the clouds

We	entrainment velocity
$w_L$	the mean large-scale vertical motion
Ζ	distance of the radiation travelled in a medium
ABL	Atmospheric Boundary Layer
BP	Black Point (lidar measurement site)
CBL	Convective Boundary Layer
CityU	City University of Hong Kong
DBL	Diurnal Boundary Layer
EPD	Environmental Protection Department (H.K.)
EZ	Entrainment Zone
HH	Hoi Ha (lidar measurement site)
НКО	Hong Kong Observatory
HT	Hok Tsui (lidar measurement site)
LCL	Lifting Condensation Level
Lidar	Light Detection and Ranging
ML	Mixing Layer
MMH	Maximum Mixing Height
MPE	Maximum Permissible Exposure
MPL	Micro Pulse Lidar
NBL	Nocturnal Boundary Layer
NT	The New Territories of Hong Kong
PBL	Planetary Boundary Layer
РМТ	Photo Multiplier Tube
Radar	Radiation Detection And Ranging
RL	Residual Layer

- RTE Radiative Transfer Equations
- SBL Stable Boundary Layer
- Sodar Sound Detection And Ranging
- TBT Tsim Bei Tsui (lidar measurement site)